

Solutions to graded exercises in Homework #7  
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Note: This assignment includes review exercises for the midterm exam.

§2.3 Ex. 7. Row reduction shows that the given  $4 \times 4$  matrix has four pivot positions. Therefore, by Theorem 8, the matrix is invertible.

§2.8 Ex. 26. Row reduction shows that the pivot columns of  $A$  are

$$\begin{bmatrix} 3 \\ -2 \\ -5 \\ -2 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 9 \\ 6 \end{bmatrix}, \begin{bmatrix} 3 \\ 7 \\ 3 \\ 3 \end{bmatrix}$$

so these vectors form a basis of  $\text{Col } A$ . Additional row reduction shows that the reduced row echelon form of  $A$  is

$$\begin{bmatrix} 1 & 0 & 3 & 0 & 2.5 \\ 0 & 1 & 2 & 0 & 1.5 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

so the system  $A\mathbf{x} = \mathbf{0}$  is equivalent to

$$\begin{aligned} x_1 + 3x_3 + 2.5x_5 &= 0 \\ x_2 + 2x_3 + 1.5x_5 &= 0 \\ x_4 + x_5 &= 0 \end{aligned}$$

with free variables  $x_3$  and  $x_5$ . Therefore, the general solution of  $A\mathbf{x} = \mathbf{b}$  may be parametrized as

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = x_3 \begin{bmatrix} -3 \\ -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} -2.5 \\ -1.5 \\ 0 \\ -1 \\ 1 \end{bmatrix}$$

and the vectors  $\begin{bmatrix} -3 \\ -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}$ ,  $\begin{bmatrix} -2.5 \\ -1.5 \\ 0 \\ -1 \\ 1 \end{bmatrix}$  form a basis of  $\text{Nul } A$ .

§1.3 Ex. 14. Row reduction shows that the pivot columns of the augmented matrix  $[A \mid \mathbf{b}]$  are just the columns of  $A$ . Since  $\mathbf{b}$  is not a pivot column, the system  $A\mathbf{x} = \mathbf{b}$  is consistent. In other words,  $\mathbf{b}$  is a linear combination of the columns of  $A$ , i.e.,  $\mathbf{b}$  belongs to  $\text{Col } A$ .

Note: We can actually say more. Since all of the columns of  $A$  are pivot columns,  $A\mathbf{x} = \mathbf{b}$  is consistent for *any*  $\mathbf{b}$ .

§1.7 Ex. 31. Since the third column of  $A$  is the sum of the first two columns, a nontrivial solution of  $A\mathbf{x} = \mathbf{0}$  is  $\mathbf{x} = \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}$ .

§1.8 Ex. 10. Row reduction shows that the reduced row echelon form of  $A$  is

$$\begin{bmatrix} 1 & 0 & 3 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

Thus the system  $A\mathbf{x} = \mathbf{0}$  is equivalent to  $x_1 + 3x_3 = x_2 + 2x_3 = x_4 = 0$

and the general solution may be parametrized as  $\mathbf{x} = x_3 \begin{bmatrix} -3 \\ -2 \\ 1 \\ 0 \end{bmatrix}$ . Thus

$\begin{bmatrix} -3 \\ -2 \\ 1 \\ 0 \end{bmatrix}$  is a basis of  $\text{Nul } A$ .